

ANALYTICAL SOLUTIONS FOR A CLASS OF FRACTAL KORTEWEG-de VRIES TYPE EQUATION

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The present study focuses on a class of Korteweg-de Vries (KdV)-type equations involving the time-space fractal scaling law derivative. The objective of this investigation is to explore their exact analytical solutions. The employment of fractal scaling law derivatives, calculus theory, and Jacobi elliptic functions, in conjunction with variable substitutions and equation transformations, facilitates the attainment of precise analytical solutions for this equation type under various conditions. The findings of the research endeavor have yielded two notable outcomes. Firstly, they have augmented the solution system for KdV-type equations. Secondly, they have furnished an effective method reference for solving other non-linear fractal partial differential equations. These contributions are instrumental in fostering the advancement of the application of fractal calculus in the domain of mathematical physics.

Keywords: fractal KdV-type equation, fractal scaling, law derivative, Jacobi elliptic function

Introduction

The subsequent classical KdV equation was introduced by Korteweg and de Vries to describe shallow water waves of long wavelength with small amplitude [1-3]:

$$\frac{\partial u}{\partial t} + 6u \frac{\partial u}{\partial x} + \frac{\partial^3 u}{\partial x^3} = 0 \quad (1)$$

It is among the most extensively studied equations in the field of mathematical physics in the present era. Consequently, a substantial corpus of literature has emerged that discusses a considerable number of non-linear KdV-type equations. A substantial body of research has been conducted by scientists and researchers concerning the precise traveling wave solutions of these equations. These investigations have been undertaken through the utilization of diverse methodologies, for examples, the variational method [4-7], the exp-function method [8, 9], tanh and sech function methods [10]. In recent years, fractal calculus has played a very important role in various application areas, such as modeling anomalous diffusion, heat transfer, seismic wave analysis, signal processing, control theory, and many other dynamical systems. The properties of several physical phenomena are found to be best described by fractal differential equations. In a recent study, the fractal scaling-law derivative was proposed as a means to investigate the relationships between the general calculus [11]

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and fractal geometry [12]. A study was conducted on a series of models of applied science that were based on the fractal scaling-law derivative [13-20].

In the present work, we consider the following fractal KdV-type equation:

$${}^{MSL}D_t^{(1)}u(x,t) + (qu + p)u {}^{MSL}D_x^{(1)}u(x,t) + r {}^{MSL}D_x^{(3)}u(x,t) = 0 \quad (2)$$

where p , q , and r are constants and the symbols, and ${}^{MSL}D_t^{(1)}$ and ${}^{MSL}D_x^{(1)}$ – the time fractal scaling-law derivative and the space fractal scaling-law derivative, respectively [13, 14]. The objective of this study is to investigate a novel class of exact solutions to eq. (2) by employing the Jacobi elliptic functions.

Preliminaries

The fractal scaling-law derivative

In this section, we will review some fundamental definitions and properties of the fractal scaling-law derivative. For a more comprehensive overview of this subject, please refer to the works of [13, 14].

Definition 1. The time fractal scaling-law derivative of $u(x, t)$ is defined:

$${}^{MSL}D_t^{(1)}u(x,t) = \alpha(\lambda, \mu, t) \frac{\partial}{\partial t} u(x,t) \quad (3)$$

where $\alpha(\lambda, \mu, t) = t^\mu \lambda^{-1} (1 - \mu)^{-1}$, the constant $\lambda > 0$, and the fractal dimension $0 \leq \mu \leq 1$.

Definition 2. The space fractal scaling-law derivative of $u(x, t)$ is defined:

$${}^{MSL}D_x^{(1)}u(x,t) = \beta(\bar{\lambda}, \bar{\mu}, x) \frac{\partial}{\partial x} u(x,t) \quad (4)$$

where $\beta(\bar{\lambda}, \bar{\mu}, x) = x^{\bar{\mu}} \bar{\lambda}^{-1} (1 - \bar{\mu})^{-1}$, the constant $\bar{\lambda} > 0$, and the fractal dimension $0 \leq \bar{\mu} \leq 1$.

Next, let us denote the scaling-law function space Ω by:

$$\Omega = \left\{ \Xi(\tau) \mid {}^{MSL}D_\tau^{(1)}\Xi(\tau) \text{ exists} \right\}$$

Theorem 1 [13, 14]. Let v is a constant, $M \in \Omega$, and $N \in \Omega$. Then:

$${}^{MSL}D_\tau^{(1)}(v) = 0 \quad (5)$$

$${}^{MSL}D_\tau^{(1)}(\lambda \tau^{1-\mu}) = 1 \quad (6)$$

$${}^{MSL}D_\tau^{(1)}[vM(\tau)] = v {}^{MSL}D_\tau^{(1)}[M(\tau)] \quad (7)$$

$${}^{MSL}D_\tau^{(1)}[M(\tau) + N(\tau)] = {}^{MSL}D_\tau^{(1)}[M(\tau)] + {}^{MSL}D_\tau^{(1)}[N(\tau)] \quad (8)$$

$${}^{MSL}D_\tau^{(1)}[M(\tau)N(\tau)] = N(\tau) {}^{MSL}D_\tau^{(1)}[M(\tau)] + M(\tau) {}^{MSL}D_\tau^{(1)}[N(\tau)] \quad (9)$$

Jacobi elliptic functions

In this section, we will briefly outline the primary characteristics of the Jacobi elliptic functions that will be utilized in this study. For a more comprehensive overview of these functions, please refer to [21, 22].

Let k be a number in $(0, 1)$, and let ξ denote a real variable. The Jacobi elliptic functions $sn(\xi, k)$, $cn(\xi, k)$, and $dn(\xi, k)$ are defined as the solutions of the system of differential equations:

$$\frac{dx}{d\xi} = yz, \quad \frac{dy}{d\xi} = -zx, \quad \frac{dz}{d\xi} = -k^2xy \tag{10}$$

that satisfy the initial conditions:

$$sn(0, k) = x(0) = 0, \quad cn(0, k) = y(0) = 1, \quad dn(0, k) = z(0) = 1$$

The parameter k is known as the modulus and satisfies $0 < k < 1$.

Equations (10) are real analytic in the variables ξ, x, y, z and k , so the basic existence theorem of ODE ensures that the Jacobi elliptic functions are smooth.

The definition immediately gives the derivatives for the functions, namely:

$$\frac{d}{d\xi} sn(\xi, k) = cn(\xi, k)dn(\xi, k) \tag{11}$$

$$\frac{d}{d\xi} cn(\xi, k) = -sn(\xi, k)dn(\xi, k) \tag{12}$$

$$\frac{d}{d\xi} dn(\xi, k) = -k^2cn(\xi, k)sn(\xi, k) \tag{13}$$

Theorem 2 [21]. As k approaches 0 from the right, we have:

$$sn(\xi, k) \rightarrow \sin(\xi), \quad cn(\xi, k) \rightarrow \cos(\xi), \quad dn(\xi, k) \rightarrow 1 \tag{14}$$

and as k approaches 1 from the left, we have:

$$sn(\xi, k) \rightarrow \tanh(\xi), \quad cn(\xi, k) \rightarrow \operatorname{sech}(\xi), \quad dn(\xi, k) \rightarrow \operatorname{sech}(\xi) \tag{15}$$

Theorem 3 [21]. For fixed $k, 0 < k < 1$, the following identities hold:

$$sn^2(\xi, k) + cn^2(\xi, k) \equiv 1 \tag{16}$$

$$k^2 sn^2(\xi, k) + dn^2(\xi, k) \equiv 1 \tag{17}$$

The solutions of eq. (2)

In this section, by using the Jacobi elliptic functions, we seek the exact solutions of eq. (2).

Firstly, by the two-scale transform [23, 24]:

$$Y = \frac{\bar{\lambda}}{x^{\bar{\mu}-1}}, \quad Z = \frac{\lambda}{t^{\mu-1}} \tag{18}$$

Equation (2) is converted into the following form:

$$\frac{\partial u}{\partial Z} + (p + qu)u \frac{\partial u}{\partial Y} + r \frac{\partial^3 u}{\partial Y^3} = 0 \quad (19)$$

Suppose eq. (19) has the traveling solution of the form:

$$u(Y, Z) = u(\xi), \quad \xi = \varepsilon Y + \omega Z \quad (20)$$

where ε and ω are constants.

Substituting eq. (20) into eq. (19) yields:

$$\omega u_\xi + p \varepsilon u u_\xi + q \varepsilon u^2 u_\xi + r \varepsilon^3 u_{\xi\xi\xi} = 0 \quad (21)$$

Integrating both sides of eq. (21) with respect to ξ , we obtain:

$$6\omega u + 3p\varepsilon u^2 + 2q\varepsilon u^3 + 6r\varepsilon^3 u_{\xi\xi} = c_1$$

Let $u_\xi = v$. Then we get:

$$6\omega u^2 + 2p\varepsilon u^3 + q\varepsilon u^4 + 6r\varepsilon^3 v^2 = c_1 u + c_2 \quad (22)$$

where c_1 and c_2 are the integration constants.

Now, if $q = 0$, we seek solutions of eq. (22) in the form:

$$u(\xi) = \frac{A_1 + A_2 \operatorname{sn}^2(\xi)}{b_1 + b_2 \operatorname{sn}(\xi)} \quad (23)$$

where A_1, A_2, b_1 and b_2 are constants to be determined.

Using eqs. (11)-(13), we get:

$$u_\xi = \frac{[2A_2 b_1 \operatorname{sn}(\xi) - A_1 b_2] \operatorname{cn}(\xi) \operatorname{dn}(\xi) + A_2 b_2 \operatorname{sn}^2(\xi) \operatorname{cn}(\xi) \operatorname{dn}(\xi)}{[b_1 + b_2 \operatorname{sn}(\xi)]^2} \quad (24)$$

We firstly take $A_2 = 0$.

By eq. (16) and eq. (17), we have:

$$\operatorname{cn}^2(\xi) = 1 - w^2, \quad \operatorname{dn}^2(\xi) = 1 - k^2 w^2 \quad (25)$$

where $w = \operatorname{sn}(\xi)$.

Substituting eqs. (23)-(25) into eq. (22), we get:

$$\begin{aligned} & 6\omega A_1^2 (b_1^2 + 2b_1 b_2 w + b_2^2 w^2) + 2p\varepsilon A_1^3 (b_1 + b_2 w) + 6r\varepsilon^3 A_1^2 b_2 (1 - k^2 w^2 - w^2 + k^2 w^4) = \\ & = c_1 A_1 (b_1^3 + 3b_1^2 b_2 w + 3b_1 b_2^2 w^2 + b_2^3 w^3) + c_2 (b_1^4 + 4b_1^3 b_2 w + 6b_1^2 b_2^2 w^2 + 4b_1 b_2^3 w^3 + b_2^4 w^4) \end{aligned}$$

By comparing the coefficients of the same power of w in the previous equation, we get:

$$6\omega A_1^2 b_1^2 + 2p\varepsilon A_1^3 b_1 + \varepsilon^3 A_1^2 b_2 = c_1 A_1 b_1^3 + c_2 b_1^4 \quad (26)$$

$$12\omega A_1^2 b_1 b_2 + 2p\varepsilon A_1^3 b_2 = 3c_1 A_1 b_1^2 b_2 + 4c_2 b_1^3 b_2 \quad (27)$$

$$6\omega A_1^2 b_2^2 - 6(1+k^2)r\varepsilon^3 A_1^2 b_2^2 = 3c_1 A_1 b_2^2 b_1 + 6c_2 b_1^2 b_2^2 \quad (28)$$

$$c_1 A_1 b_2^3 + 4c_2 b_2^3 b_1 = 0 \quad (29)$$

$$6r\varepsilon^3 A_1^2 b_2^2 k^2 = c_2 b_2^4 \quad (30)$$

We can get infinitely many solutions for the system of eqs. (26)-(30). For example, solving the system of equations with the help of MAPLE we get the following set of solutions:

$$A_1 = 6p^{-1}r\varepsilon^2(k^2 - 1), \quad b_1 = b_2 = 1, \quad \omega = r\varepsilon^3(1 - 5k^2)$$

Thus, by eq. (18), we obtain the exact solution of eq. (2):

$$u(x,t) = \frac{6p^{-1}r\varepsilon^2(k^2 - 1)}{1 + \operatorname{sn}\left[\frac{\varepsilon\bar{\lambda}}{x^{\bar{\mu}-1}} + \frac{r\varepsilon^3\omega\lambda(1 - 5k^2)}{t^{\mu-1}}\right]} \quad (31)$$

Then, we take $b_2 = 0$. In this case, eq. (23) becomes:

$$u(\xi) = A + B\operatorname{sn}(\xi) \quad (32)$$

where $A = A_1/b_1, B = A_2/b_1$.

Substituting eq. (32) into eq. (22), we have:

$$3\omega(A^2 + 2ABw^2 + B^2w^4) + p\varepsilon(A^3 + 3A^2Bw^2 + 3AB^2w^4 + B^3w^6) + 12r\varepsilon^3B^2w^2(1 - k^2w^2 - w^2 + k^2w^4) = c_1A + c_1Bw^2 + c_2 \quad (33)$$

By comparing the coefficients of the same power of w in the previous equation, we get:

$$3\omega A^2 + p\varepsilon A^3 = c_1A + c_2 \quad (34)$$

$$2\omega AB + p\varepsilon A^2B + 4r\varepsilon^3B^2 = c_1B \quad (35)$$

$$\omega B^2 - p\varepsilon AB^2 - 4(1+k^2)r\varepsilon^3B^2 = 0 \quad (36)$$

$$p\varepsilon B^3 + 12r\varepsilon^3B^2k^2 = 0 \quad (37)$$

Solving the system of equations, we get the following set of solutions:

$$A = 0, \quad B = 1, \quad \varepsilon^2 = -p(12rk^2)^{-1}, \quad c_1 = 12r\varepsilon^3, \quad c_2 = 0, \quad \omega = 4r\varepsilon^3(1+k^2)$$

Hence, we obtain the exact solution of eq. (2) in the form:

$$u = sn^2 \left[\frac{l\bar{\lambda}}{x^{\bar{\mu}-1}} + \frac{4r\varepsilon^3\omega\lambda(1+k^2)}{t^{\mu-1}} \right] \quad (38)$$

Next, we consider the case $q \neq 0$. In this case, we seek solutions of eq. (22) in the form:

$$u(\xi) = \frac{Msn(\xi)}{m_0 + m_1sn(\xi) + m_2cn(\xi)} \quad (39)$$

By using the same method as was used previously, we can obtain the following set of solutions:

$$M = m_0 = m_1 = m_2 = 1, \quad \varepsilon^2 = -q \left[3r(1-k^2) \right]^{-1}, \quad \omega = -r\varepsilon^3(2-k^2) \quad (40)$$

From eq. (40), we obtain the exact solution of eq. (2) in the form:

$$u(\xi) = \frac{sn(\xi)}{1 + sn(\xi) + cn(\xi)}, \quad \xi = \frac{\varepsilon\bar{\lambda}}{x^{\bar{\mu}-1}} + \frac{r\varepsilon^3\omega\lambda(2-k^2)}{t^{\mu-1}} \quad (41)$$

Remark 1. By eq. (14), as k approaches 0 from the right, eq. (31) becomes:

$$u(x, t) = \frac{-6p^{-1}r\varepsilon^2}{1 + \sin \left(\frac{\varepsilon\bar{\lambda}}{x^{\bar{\mu}-1}} + \frac{r\varepsilon^3\omega\lambda}{t^{\mu-1}} \right)}$$

and eq. (38) becomes:

$$u = \sin^2 \left(\frac{l\bar{\lambda}}{x^{\bar{\mu}-1}} + \frac{4r\varepsilon^3\omega\lambda}{t^{\mu-1}} \right)$$

Remark 2. By eq. (15), as k approaches 1 from the right, eq. (41) becomes:

$$u(\xi) = \frac{\tanh(\xi)}{1 + \tanh(\xi) + \operatorname{sech}(\xi)}, \quad \xi = \frac{\varepsilon\bar{\lambda}}{x^{\bar{\mu}-1}} + \frac{r\varepsilon^3\omega\lambda}{t^{\mu-1}}$$

Conclusion

In this paper, we seek analytical solutions for a class of KdV-type equations involving Yang's fractal scaling-law derivative. The advent of Jacobi elliptic functions has led to the discovery of novel exact analytical solutions to this class of equations. The methodologies delineated in this article can be extrapolated to other non-linear fractal differential equations, e.g., the fractal Richards equation [25], and the fractional order can be determined by the two-scale fractal dimensions [26, 27].

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